



MxL82403 and MxL82423

16-Bit SPI GPIO Expander with Reset Input

Data Sheet

General Description

The MxL82403 and MxL82423 are 16-bit GPIO expanders with an SPI interface. After power-up, the MxL82403 and MxL82423 have internal 100k Ω pull-up resistors on each I/O pin that can be individually enabled.

In addition, the GPIOs on the MxL82403 and MxL82423 can individually be controlled and configured. As outputs, the GPIOs can be outputs that are high, low or in three-state mode. The three-state mode feature is useful for applications where the power is removed from the remote devices, but they may still be connected to the GPIO expander.

As inputs, the internal pull-up resistors can be enabled or disabled and the input polarity can be inverted. The interrupt behavior is configurable. It can be set to trigger on a rising edge, falling edge, or both edges. The interrupt condition is cleared either when the input returns to its original state or when the current input state is read.

By default, the MxL82403 has the IRQ enabled while the MxL82423 has the IRQ disabled.

The MxL82403 is available in a 7.8mm $\times$ 4.4mm 24-pin TSSOP package, while the MxL82423 is available in a 4mm $\times$ 4mm 24-pin QFN package.

Applications

- Telecom, networking, and server platforms (BMC)
- GPIO expansion for embedded systems
- Industrial automation and robotics
- IoT and smart sensor devices
- System monitoring and control
- Power sequencing and control
- Human interface control (LEDs, keypads, switches)
- Test and measurement equipment
- Systems using GPIO-limited processors

Features

- 1.62V to 5.5V operating voltage
- 16 General Purpose I/Os (GPIOs)
- Maximum standby current of 1 μ A at +1.8V
- SPI Bus interface
- SPI Clock frequency up to 26MHz
- Integrated level shifters
- Individually programmable inputs
 - Internal pull-up resistors
 - Polarity inversion
 - Individual interrupt enable
 - Rising edge and/or falling edge interrupt
 - Input filter
- Individually programmable outputs
 - Output level control
 - Output three-state control
- Open-drain active low interrupt output
- Active low reset input
- 3kV HBM ESD protection per *JESD22-A114F*
- $\pm$ 100mA latch-up performance per *JESD78B*

Revision History

Document No.	Release Date	Change Description
304DSR02	July 30, 2026	Initial final release.

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Specifications

Absolute Maximum Ratings

Important: The stresses above what is listed under the following table may cause permanent damage to the device. This is a stress rating only—functional operation of the device above what is listed under the following table or any other conditions beyond what MaxLinear recommends is not implied. Exposure to conditions above the recommended extended periods of time may affect device reliability. Solder reflow profile is specified in the *IPC/JEDEC J-STD-020C* standard.

Table 1: Absolute Maximum Ratings

Parameter	Minimum	Maximum	Unit
Power Supply Voltage	-	6	V
Supply Current	-	160	mA
Ground Current	-	200	mA
External Current limit of each GPIO	-	25	mA
Total Current limit for GPIO[15:8] and GPIO[7:0]	-	100	mA
Total Current limit for GPIO[15:0]	-	200	mA
Total Supply Current sourced by all GPIOs	-	160	mA
Operating Temperature	-40	+85	°C
Storage Temperature	-65	+150	°C
Power Dissipation	-	200	mW

Thermal Information

Table 2: Thermal Information

Symbol	Thermal Metric	Typical		Unit
		QFN-24	TSSOP-24	
$\theta_{JC(top)}$	Junction-to-Case Top Thermal Resistance	64	38	°C/W
$\theta_{JC(bottom)}$	Junction-to-Case Bottom Thermal Resistance	26	61	
θ_{JB}	Junction-to-Board Thermal Resistance	32	60	
θ_{JA}	Junction-to-Ambient Thermal Resistance	51	83	
Ψ_{JT}	Junction-to-Case Top Thermal Characterization	9	2	
Ψ_{JB}	Junction-to-Board Thermal Characterization	31	56	

Electrical Characteristics

DC Electrical Characteristics

Unless otherwise noted, $T_A = -40^{\circ}$ to $+85^{\circ}\text{C}$, V_{CC} is from 1.62V to 5.5V.

Table 3: DC Electrical Characteristics

Symbol	Parameter	Limits $1.8\text{V} \pm 10\%$		Limits $2.5\text{V} \pm 10\%$		Limits $3.3\text{V} \pm 10\%$		Limits $5.0\text{V} \pm 10\%$		Units	Conditions
		Min	Max	Min	Max	Min	Max	Min	Max		
V_{IL}	Input Low Voltage	-0.3	0.2	-0.3	0.5	-0.3	0.8	-	$0.3 \cdot V_{CC}$	V	Note 1
V_{IH}	Input High Voltage	1.4	5.5	1.8	5.5	$0.7 \cdot V_{CC}$	5.5	$0.7 \cdot V_{CC}$	-	V	Note 1
V_{OL}	Output Low Voltage	-	0.4	-	0.4	-	0.4	-	0.4	V V V	$I_{OL} = 1.5\text{mA}$ $I_{OL} = 4\text{mA}$ $I_{OL} = 6\text{mA}$ Note 2 and Note 4
V_{OL}	Output Low Voltage	-	0.5	-	0.5	-	0.5	-	0.5	V	$I_{OL} = 8\text{mA}$ Note 3
V_{OH}	Output High Voltage	1.4	-	1.8	-	2.0	-	2.0	-	V V V	$I_{OL} = -0.2\text{mA}$ $I_{OL} = -2\text{mA}$ $I_{OL} = -4\text{mA}$ Note 2
V_{OH}	Output High Voltage	1.2	-	1.8	-	2.6	-	4.1	-	V	$I_{OH} = -8\text{mA}$ Note 3
I_{IL}	Input Low Leakage Current	-	± 10	-	± 10	-	± 10	-	± 10	μA	-
I_{IH}	Input High Leakage Current	-	± 10	-	± 10	-	± 10	-	± 10	μA	-
C_{IN}	Input Pin Capacitance	-	5	-	5	-	5	-	5	pF	-
I_{CC}	Power Supply Current	-	0.5	-	1.0	-	2.0	-	4	μA	Note 5
I_{CC}	Power Supply Current	-	0.6	-	1.2	-	2.4	-	5	μA	Note 6
I_{CCS}	Standby Current	-	1	-	2	-	5	-	7	μA	Note 7
R_{GPIO}	GPIO Pull-up Resistance	60	140	60	140	60	140	60	140	$k\Omega$	$100k\Omega \pm 40\%$
$R_{RESET\#}$	Reset# Pull-up Resistance	30	85	35	85	35	85	35	85	$k\Omega$	$60k\Omega \pm 40\%$

1. For SPI input signals (SI, SCK) and GPIOs.

2. For SPI output signal SO.

3. For GPIOs.

4. For IRQ# signal.

5. Test 1: SCL frequency is 10MHz with internal pull-ups disabled. All GPIOs are configured as inputs. All inputs are steady at VCC or GND. Outputs are floating or in the tri-state mode.

6. Test 2: SCL frequency is 10MHz with internal pull-ups enabled. All GPIOs are configured as inputs. All inputs are steady at VCC or GND. Outputs are floating or in the tri-state mode.

7. Test 3: All inputs are steady at VCC or GND to minimize standby current. If internal pull-up is enabled, input voltage level should be the same as VCC. SCL, and SI are at GND. CS# is at VCC. All GPIOs are configured as inputs. Outputs are left floating or in tri-state mode.

AC Electrical Characteristics

Unless otherwise noted, $T_A = -40^\circ$ to $+85^\circ\text{C}$, V_{CC} is from 1.62V to 5.5V.

Table 4: AC Electrical Characteristics

Symbol	Parameter	Limits 1.8V±10%			Limits 2.5V±10%			Limits 3.3V±10%			Limits 5V±10%			Unit	Conditions
		Min	Typ	Max	Min	Typ	Max	Min	Typ	Max	Min	Typ	Max		
f_{SCL}	Operating Frequency	-	-	15	-	-	26	-	-	26	-	-	26	MHz	-
T_{CSS}	CS# to SCL Setup Time	10	-	-	5	-	-	5	-	-	5	-	-	ns	-
T_{CSH}	CS# to SCL Hold Time	30	-	-	28	-	-	25	-	-	25	-	-	ns	-
T_{DO}	SCL Fall to SO Valid Time	-	-	30	-	-	17	-	-	17	-	-	17	ns	$C_L = 30\text{ pF}$
T_{DS}	SI to SCL Setup Time	15	-	-	10	-	-	10	-	-	10	-	-	ns	-
T_{DH}	SI to SCL Hold Time	20	-	-	5	-	-	5	-	-	5	-	-	ns	-
T_{CP}	SCL Period	66	-	-	38	-	-	38	-	-	38	-	-	ns	$T_{CH} + T_{CL}$
T_{CH}	SCL HIGH Time	26	-	-	15	-	-	15	-	-	15	-	-	ns	-
T_{CL}	SCL LOW Time	40	-	-	23	-	-	23	-	-	23	-	-	ns	-
T_{CSW}	CS# HIGH Pulse Width	5	-	-	5	-	-	5	-	-	10	-	-	ns	-
T_{D9}	GPI Output Data Valid Time	40	-	-	30	-	-	20	-	-	20	-	-	ns	-
T_{D13}	SPI Input Pin Interrupt Clear	-	-	250	-	-	250	-	-	250	-	-	250	ns	-

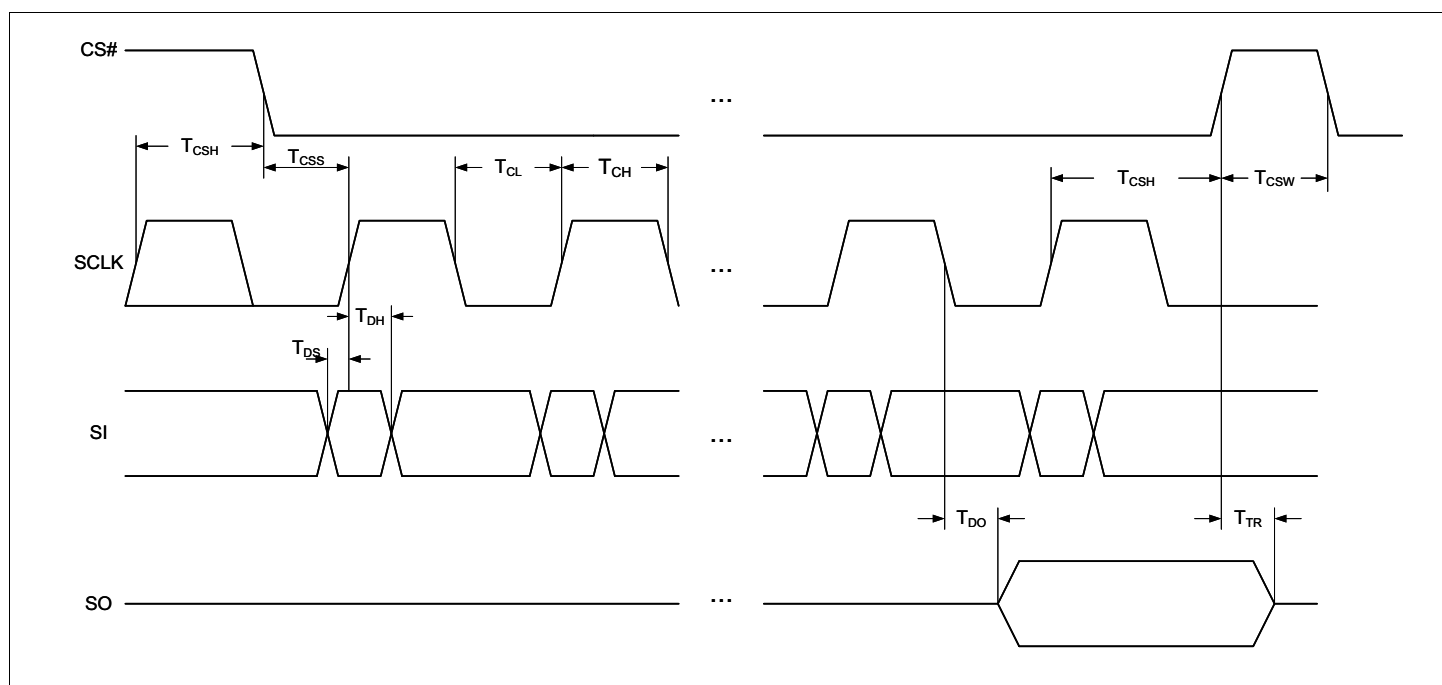


Figure 1: SPI Bus Timing Diagram

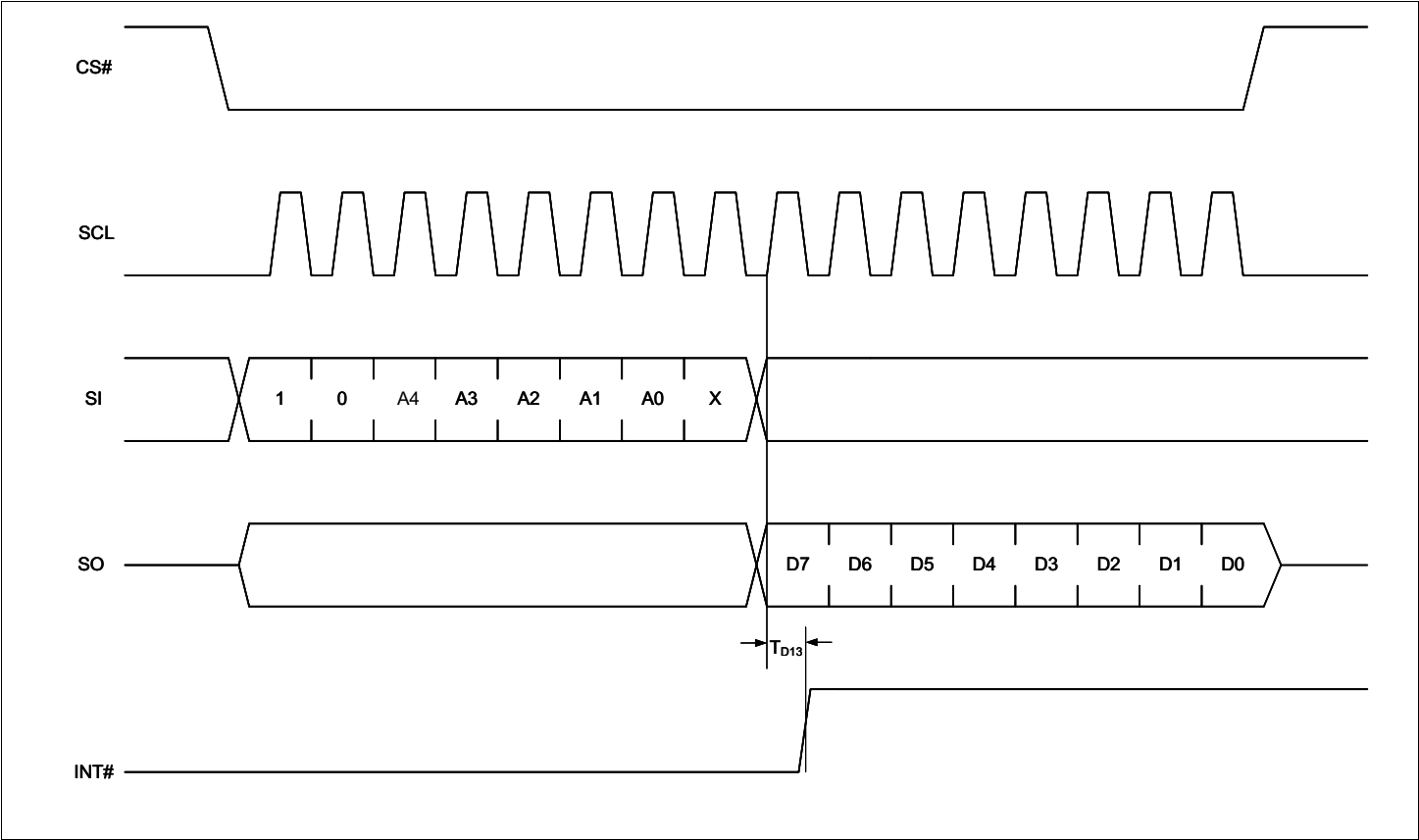


Figure 2: Read Input Port to Clear GPIO INT

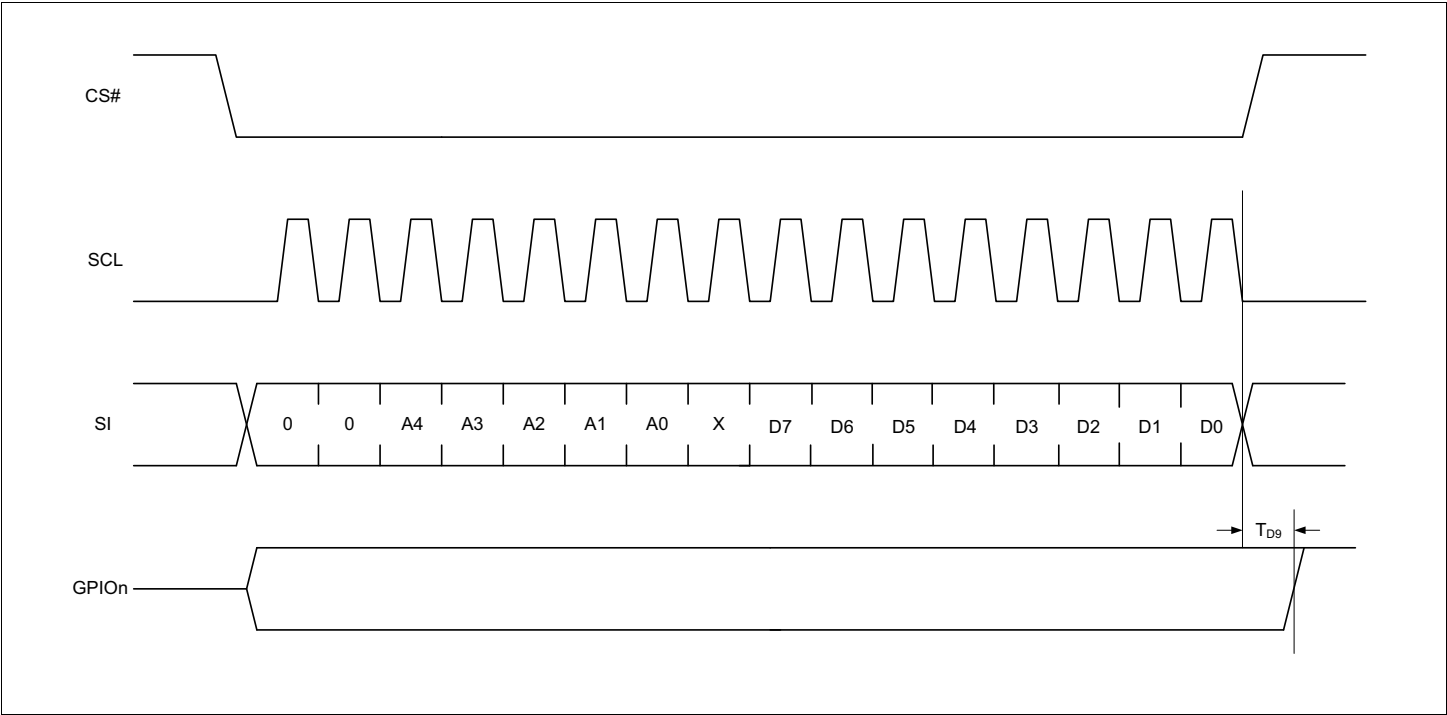


Figure 3: SPI Write out to GPIO Switch

Pin Configuration

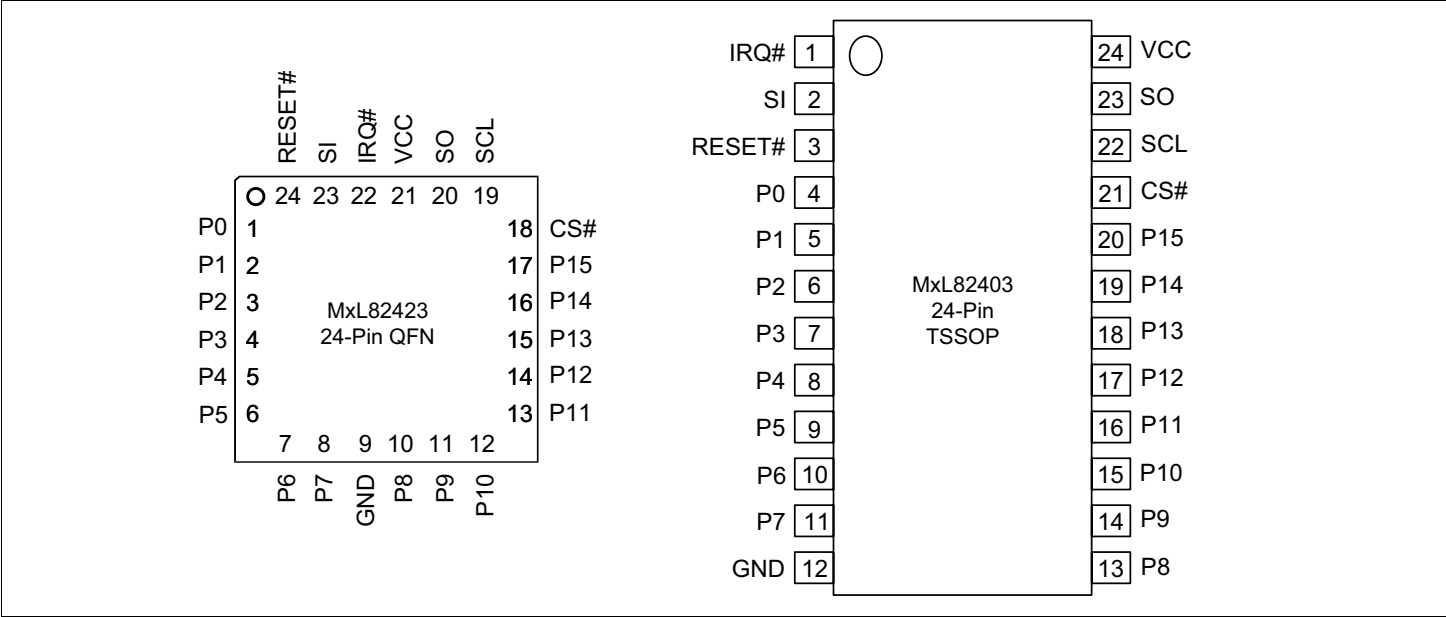


Figure 4: Pin Configuration (Top View)

Pin Description

Table 5: Pin Description

Name	QFN-24 Pin#	TSSOP-24 Pin#	Type	Description
SPI Interface				
SO	20	23	O	SPI serial data output.
SCL	19	22	I	SPI bus serial input clock.
IRQ#	22	1	OD	Interrupt output (open-drain, active LOW).
CS#	18	21	I	SPI bus chip select.
SI	23	2	I	SPI serial data input.
RESET#	24	3	I	Reset (active LOW) - A longer than 40ns LOW pulse on this pin resets the internal registers and all GPIOs are configured as inputs.
GPIOs				
P0	1	4	I/O	General purpose I/Os P0-P7. All GPIOs are configured as inputs upon power-up or after a reset.
P1	2	5	I/O	
P2	3	6	I/O	
P3	4	7	I/O	
P4	5	8	I/O	
P5	6	9	I/O	
P6	7	10	I/O	
P7	8	11	I/O	

Table 5: Pin Description (Continued)

Name	QFN-24 Pin#	TSSOP-24 Pin#	Type	Description
P8	10	13	I/O	General purpose I/O P8-P15. All GPIOs are configured as inputs upon power-up or after a reset.
P9	11	14	I/O	
P10	12	15	I/O	
P11	13	16	I/O	
P12	14	17	I/O	
P13	15	18	I/O	
P14	16	19	I/O	
P15	17	20	I/O	
Ancillary Signals				
VCC	21	24	Pwr	1.62V to 5.5V VCC supply voltage.
GND	9	12	Pwr	Power supply common, ground.
GND	Center Pad	-	Pwr	The exposed pad at the bottom surface of the package is designed for thermal performance. Use of a center pad on the PCB is strongly recommended for thermal conductivity as well as to provide mechanical stability of the package on the PCB. The center pad is recommended to be solder masked defined with opening size less than or equal to the exposed thermal pad on the package bottom to prevent solder bridging to the outer leads of the device. Thermal vias must be connected to GND plane as the thermal pad of package is at GND potential.

Note: Pin type: I = Input, O = Output, I/O = Input/Output, OD = Output Open Drain.

Block Diagram

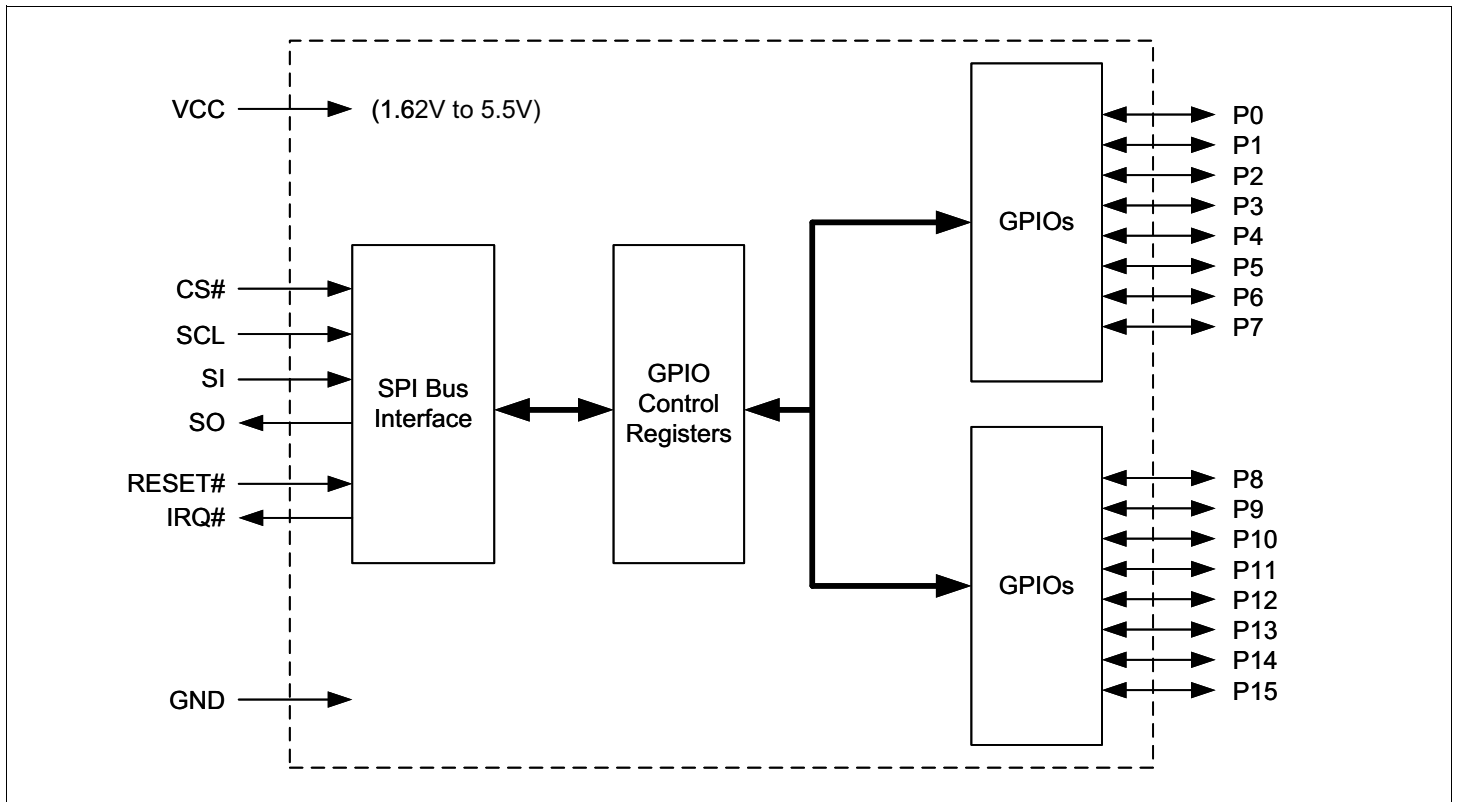


Figure 5: Functional Block Diagram

Functional Description

SPI Bus Interface

The SPI interface consists of four lines: serial clock (SCL), chip select (CS#), slave output (SO) and slave input (SI). The serial clock, slave output, and slave input can be as fast as 26MHz. To access the device in the SPI mode, the CS# signal is asserted by the SPI master, then the SPI master starts toggling the SCL signal with the appropriate transaction information. The first bit sent by the SPI master includes whether it is a read or write transaction and the register being accessed. See the following table.

Table 6: SPI Command Byte Format

Bit	Function
7	Read/Write# Logic 1 = Read Logic 0 = Write
6:1	Command Byte
0	Reserved

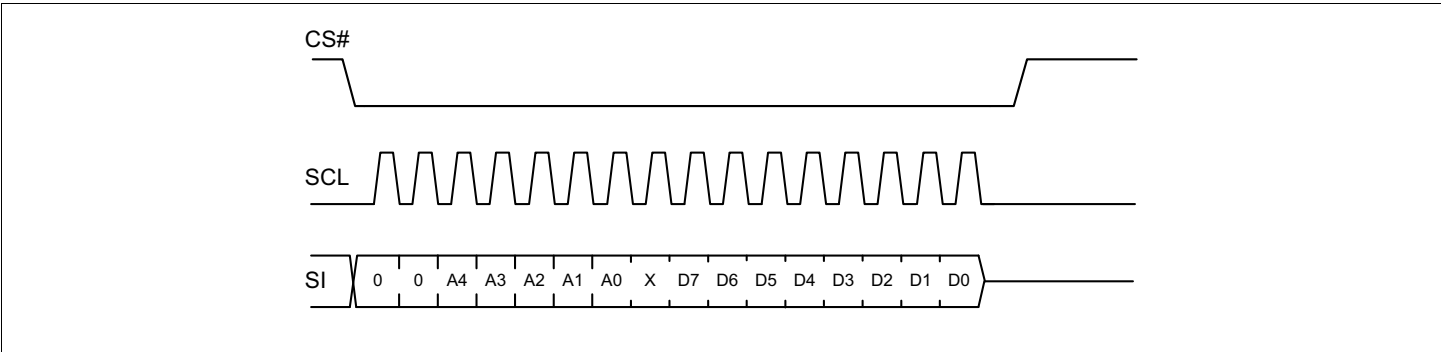


Figure 6: SPI Write

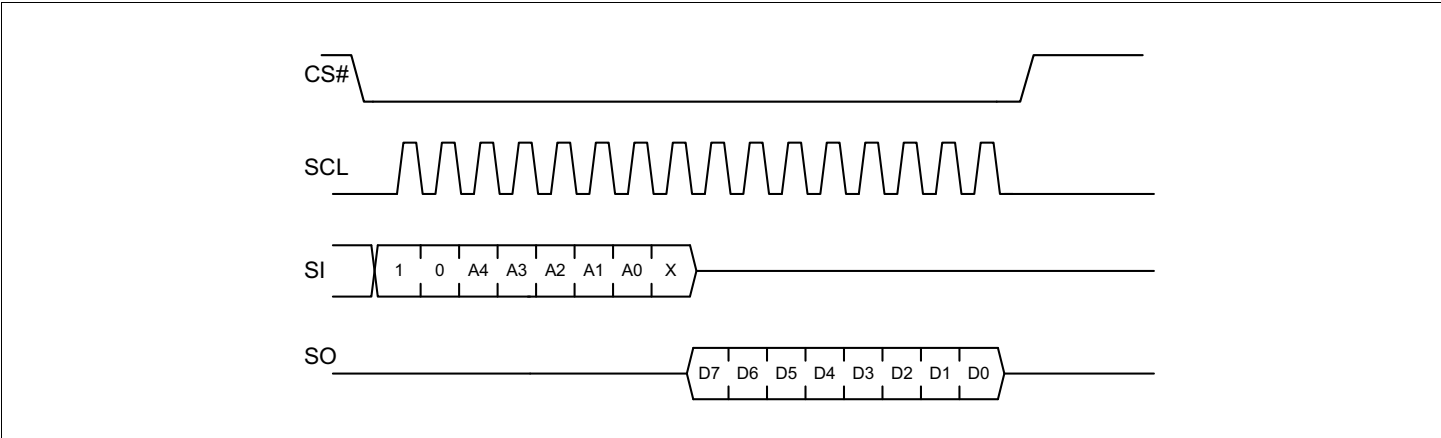


Figure 7: SPI Read

After the last read or write transaction, the SPI master sets the SCL signal back to its idle state (LOW).

SPI Command Byte

An SPI command byte is sent by the SPI master following the slave address. The command byte indicates the address offset of the register that is accessed. The following table lists the command bytes for each register.

Table 7: Command Byte (Register Address)

Command Byte	Register Name Description	Read/Write	Default Values
0x00	GSR1—GPIO State for P0-P7	Read-Only	0xFF
0x01	GSR2—GPIO State for P8-P15	Read-Only	0xFF
0x02	OCR1—Output Control for P0-P7	Read/Write	0xFF
0x03	OCR2—Output Control for P8-P15	Read/Write	0xFF
0x04	PIR1—Input Polarity Inversion for P0-P7	Read/Write	0x00
0x05	PIR2—Input Polarity Inversion for P8-P15	Read/Write	0x00
0x06	GCR1—GPIO Configuration for P0-P7	Read/Write	0xFF
0x07	GCR2—GPIO Configuration for P8-P15	Read/Write	0xFF
0x08	PUR1—Input Internal Pull-up Resistor Enable/Disable for P0-P7	Read/Write	0x00
0x09	PUR2—Input Internal Pull-up Resistor Enable/Disable for P8-P15	Read/Write	0x00
0x0A	IER1—Input Interrupt Enable for P0-P7	Read/Write	0xFF (MxL82403) 0x00 (MxL82423)
0x0B	IER2—Input Interrupt Enable for P8-P15	Read/Write	0xFF (MxL82403) 0x00 (MxL82423)
0x0C	TSCR1—Output Three-State Control for P0-P7	Read/Write	0x00
0x0D	TSCR2—Output Three-State Control for P8-P15	Read/Write	0x00
0x0E	ISR1—Input Interrupt Status for P0-P7	Read	0x00
0x0F	ISR2—Input Interrupt Status for P8-P15	Read	0x00
0x10	REIR1—Input Rising Edge Interrupt Enable for P0-P7	Read/Write	0x00
0x11	REIR2—Input Rising Edge Interrupt Enable for P8-P15	Read/Write	0x00
0x12	FEIR1—Input Falling Edge Interrupt Enable for P0-P7	Read/Write	0x00
0x13	FEIR2—Input Falling Edge Interrupt Enable for P8-P15	Read/Write	0x00
0x14	IFR1—Input Filter Enable/Disable for P0-P7	Read/Write	0xFF
0x15	IFR2—Input Filter Enable/Disable for P8-P15	Read/Write	0xFF

Interrupts

The following table lists the interrupt behavior of the different register settings for the MxL82403 and MxL82423 devices.

Table 8: Interrupt Generation and Clearing

GCR Bit	IER Bit	REIR Bit	FEIR Bit	IFR Bit	Interrupt Generated By:	Interrupt Cleared By:
1	0	X	X	X	No interrupts enabled (default).	N/A
1	1	0	0	0	A rising or falling edge on the input.	Reading the GSR register or if the input changes back to its previous state (state of input during last read to GSR)
				1	A rising or falling edge on the input and remains in the new state for more than 1075ns.	
1	1	1	0	0	A rising edge on the input.	Reading the GSR register
				1	A rising edge on the input and remains high for more than 1075ns.	
1	1	0	1	0	A falling edge on the input.	Reading the GSR register
				1	A falling edge on the input and remains low for more than 1075ns.	
1	1	1	1	0	A rising or falling edge on the input.	Reading the GSR register
				1	A rising or falling edge on the input and remains in the new state for more than 1075ns.	
0	x	x	x	x	No interrupts in output mode.	N/A

Register Description

GPIO State Register 1 (GSR1)—Read-Only

The status of P7–P0 can be read via this register. A read shows the current state of these pins (or the inverted state of these pins if enabled via the PIR Register). Reading this register clears an input interrupt (For complete details, see [Table 8](#) on page 10). Reading this register also returns the last value written to the OCR register for any pins that are configured as outputs (note that this is not the same as the state of the actual output pin since the output pin can be in three-state mode). A write to this register has no effect. The MSB of this register corresponds with P7 and the LSB of this register corresponds with P0.

GPIO State Register 2 (GSR2)—Read-Only

The status of P15–P8 can be read via this register. A read shows the current state of these pins (or the inverted state of these pins if enabled via the PIR Register). Reading this register clears an input interrupt (For complete details, see [Table 8](#) on page 10). Reading this register also returns the last value written to the OCR register for any pins that are configured as outputs (note that this is not the same as the state of the actual output pin since the output pin can be in three-state mode). A write to this register has no effect. The MSB of this register corresponds with P15 and the LSB of this register corresponds with P8.

Output Control Register 1 (OCR1)—Read/Write

When P7–P0 are defined as outputs, they can be controlled by writing to this register. Reading this register returns the last value written to it, however, this value may not be the actual state of the output pin since these pins can be in three-state mode. The MSB of this register corresponds with P7 and the LSB of this register corresponds with P0.

Output Control Register 2 (OCR2)—Read/Write

When P15–P8 are defined as outputs, they can be controlled by writing to this register. Reading this register returns the last value written to it, however, this value may not be the actual state of the output pin since these pins can be in three-state mode. The MSB of this register corresponds with P15 and the LSB of this register corresponds with P8.

Input Polarity Inversion Register 1 (PIR1)—Read/Write

When P7–P0 are defined as inputs, this register inverts the polarity of the input value read from the Input Port Register. If the corresponding bit in this register is set to 1, the value of this bit in the GSR Register is the inverted value of the input pin. If the corresponding bit in this register is set to 0, the value of this bit in the GSR Register is the actual value of the input pin. The MSB of this register corresponds with P7 and the LSB of this register corresponds with P0.

Input Polarity Inversion Register 2 (PIR2)—Read/Write

When P15–P8 are defined as inputs, this register inverts the polarity of the input value read from the Input Port Register. If the corresponding bit in this register is set to 1, the value of this bit in the GSR Register is the inverted value of the input pin. If the corresponding bit in this register is set to 0, the value of this bit in the GSR Register is the actual value of the input pin. The MSB of this register corresponds with P15 and the LSB of this register corresponds with P8.

GPIO Configuration Register 1 (GCR1)—Read/Write

This register configures the GPIOs as inputs or outputs. Upon power-up or after a reset, the GPIOs are configured as inputs by default. Setting these bits to 0 enables the GPIOs as outputs. Setting these bits to 1 enables the GPIOs as inputs. The MSB of this register corresponds with P7 and the LSB of this register corresponds with P0.

GPIO Configuration Register 2 (GCR2)—Read/Write

This register configures the GPIOs as inputs or outputs. Upon power-up or after a reset, the GPIOs are configured as inputs by default. Setting these bits to 0 enables the GPIOs as outputs. Setting these bits to 1 enables the GPIOs as inputs. The MSB of this register corresponds with P15 and the LSB of this register corresponds with P8.

Input Internal Pull-up Enable/Disable Register 1 (PUR1)—Read/Write

This register enables/disables the internal pull-up resistors for an input. Upon power-up or after a reset, the internal pull-up resistors are disabled by default. Writing a 1 to these bits enables the internal pull-up resistors. Writing a 0 to these bits disables the internal pull-up resistors. The MSB of this register corresponds with P7 and the LSB of this register corresponds with P0.

Input Internal Pull-up Enable/Disable Register 2 (PUR2)—Read/Write

This register enables/disables the internal pull-up resistors for an input. Upon power-up or after a reset, the internal pull-up resistors are disabled by default. Writing a 1 to these bits enables the internal pull-up resistors. Writing a 0 to these bits disables the internal pull-up resistors. The MSB of this register corresponds with P15 and the LSB of this register corresponds with P8.

Input Interrupt Enable Register 1 (IER1)—Read/Write

This register controls interrupt generation for the input pins. Writing a 1 to a bit enables interrupts for the corresponding input pin, while writing a 0 disables interrupts. Upon power-up or after a reset, interrupts are enabled by default on the MxL82403 and disabled by default on the MxL82423.

For detailed interrupt behavior under different register configurations, see [Table 8](#) on page 10. When the GCR bit is 0, interrupts are not generated for output pins. The MSB of this register corresponds to P7, and the LSB corresponds to P0.

Input Interrupt Enable Register 2 (IER2)—Read/Write

This register controls interrupt generation for the input pins. Writing a 1 to a bit enables interrupts for the corresponding input pin, while writing a 0 disables interrupts. Upon power-up or after a reset, interrupts are enabled by default on the MxL82403 and disabled by default on the MxL82423.

For detailed interrupt behavior under different register configurations, see [Table 8](#) on page 10. When the GCR bit is 0, interrupts are not generated for output pins. The MSB of this register corresponds to P15, and the LSB corresponds to P8.

Output Three-State Control Register 1 (TSCR1)—Read/Write

This register can enable/disable the three-state mode of an output. Writing a 1 to these bits enables the three-state mode for the corresponding output pins. The MSB of this register corresponds with P7 and the LSB of this register corresponds with P0.

Output Three-State Control Register 2 (TSCR2)—Read/Write

This register can enable/disable the three-state mode of an output. Writing a 1 to these bits enables the three-state mode for the corresponding output pins. The MSB of this register corresponds with P15 and the LSB of this register corresponds with P8.

Input Interrupt Status Register 1 (ISR1)—Read-Only

This register reports the input pins that have generated an interrupt. For complete details of the interrupt behavior for various register settings, see [Table 8](#) on page 10. The MSB of this register corresponds with P7 and the LSB of this register corresponds with P0.

Input Interrupt Status Register 2 (ISR2)—Read-Only

This register reports the input pins that have generated an interrupt. For complete details of the interrupt behavior for various register settings, see [Table 8](#) on page 10. The MSB of this register corresponds with P15 and the LSB of this register corresponds with P8.

Input Rising Edge Interrupt Enable Register 1 (REIR1)—Read/Write

Writing a 1 to these bits enables the corresponding input to generate an interrupt on the rising edge. For complete details of the interrupt behavior for various register settings, see [Table 8](#) on page 10. The MSB of this register corresponds with P7 and the LSB of this register corresponds with P0.

Input Rising Edge Interrupt Enable Register 2 (REIR2)—Read/Write

Writing a 1 to these bits enables the corresponding input to generate an interrupt on the rising edge. For complete details of the interrupt behavior for various register settings, see [Table 8](#) on page 10. The MSB of this register corresponds with P15 and the LSB of this register corresponds with P8.

Input Falling Edge Interrupt Enable Register 1 (FEIR1)—Read/Write

Writing a 1 to these bits disables the level-sensitive interrupt logic and enables the falling edge interrupt logic if the corresponding GPIO pin is configured as an input. For complete details of the interrupt behavior for various register settings, see [Table 8](#) on page 10. The MSB of this register corresponds with P7 and the LSB of this register corresponds with P0.

Input Falling Edge Interrupt Enable Register 2 (FEIR2)—Read/Write

Writing a 1 to these bits disables the level-sensitive interrupt logic and enables the falling edge interrupt logic if the corresponding GPIO pin is configured as an input. For complete details of the interrupt behavior for various register settings, see [Table 8](#) on page 10. The MSB of this register corresponds with P15 and the LSB of this register corresponds with P8.

Input Filter Enable Register 1 (IFR1)Read/Write

By default, the input filters are enabled (IFR = 0xFF). When the input filters are enabled, any pulse that is greater than 1075ns generates an interrupt (if enabled). Pulses that are less than 190ns are filtered and do not generate an interrupt. Pulses in between this range may or may not generate an interrupt. Writing a 0 to these bits disables the input filter for the corresponding inputs. With the input filters disabled, any change on the inputs generates an interrupt (if enabled). For complete details of the interrupt behavior for various register settings, see [Table 8](#) on page 10. The MSB of this register corresponds with P7 and the LSB of this register corresponds with P0.

Input Filter Enable Register 2 (IFR2)—Read/Write

By default, the input filters are enabled (IFR = 0xFF). When the input filters are enabled, any pulse that is greater than 1075ns generates an interrupt (if enabled). Pulses that are less than 190ns are filtered and do not generate an interrupt. Pulses in between this range may or may not generate an interrupt. Writing a 0 to these bits disables the input filter for the corresponding inputs. With the input filters disabled, any change on the inputs generates an interrupt (if enabled). For complete details of the interrupt behavior for various register settings, see [Table 8](#) on page 10. The MSB of this register corresponds with P15 and the LSB of this register corresponds with P8.

Mechanical Dimensions

TSSOP-24

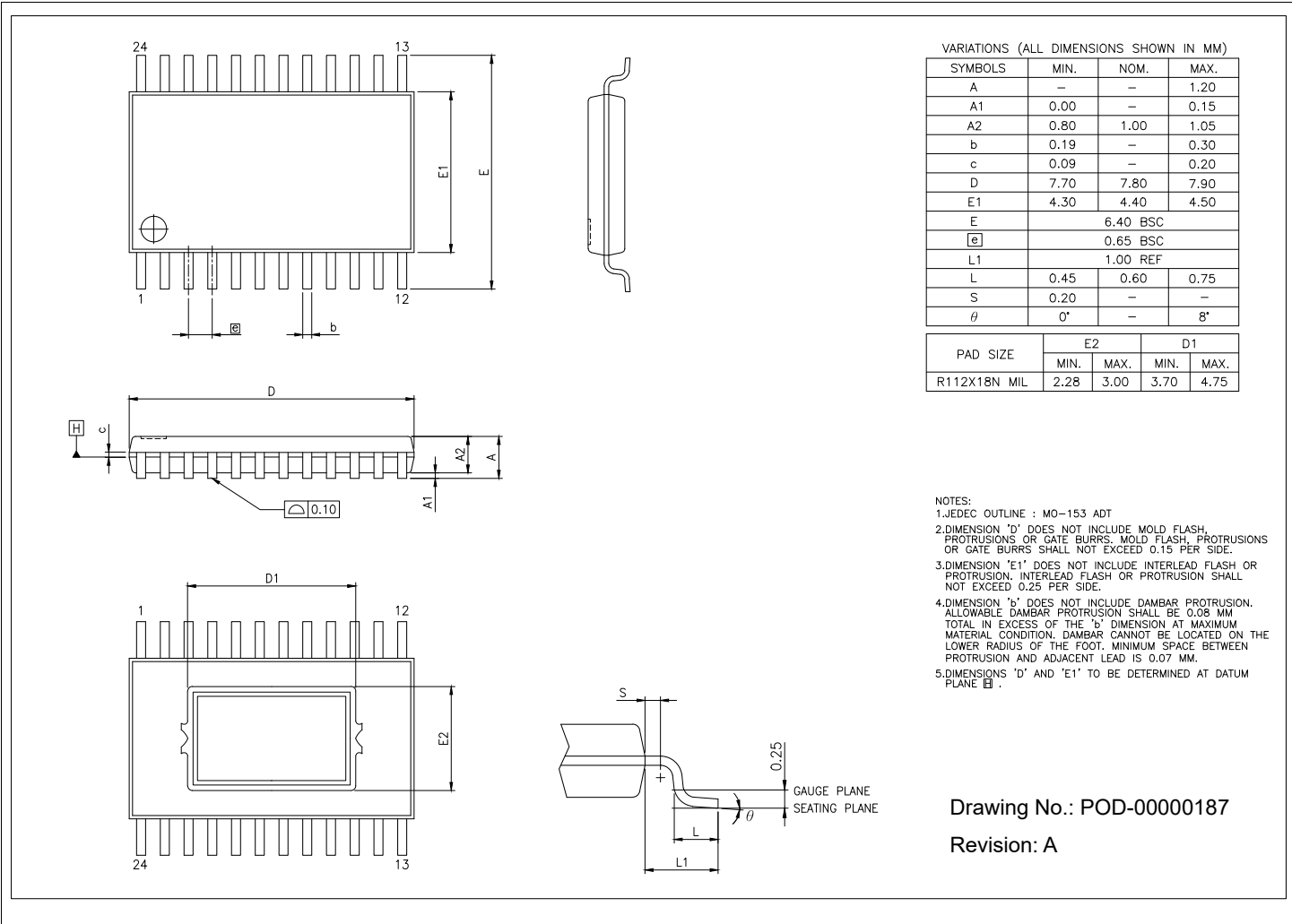


Figure 8: TSSOP-24 Mechanical Dimensions

QFN-24

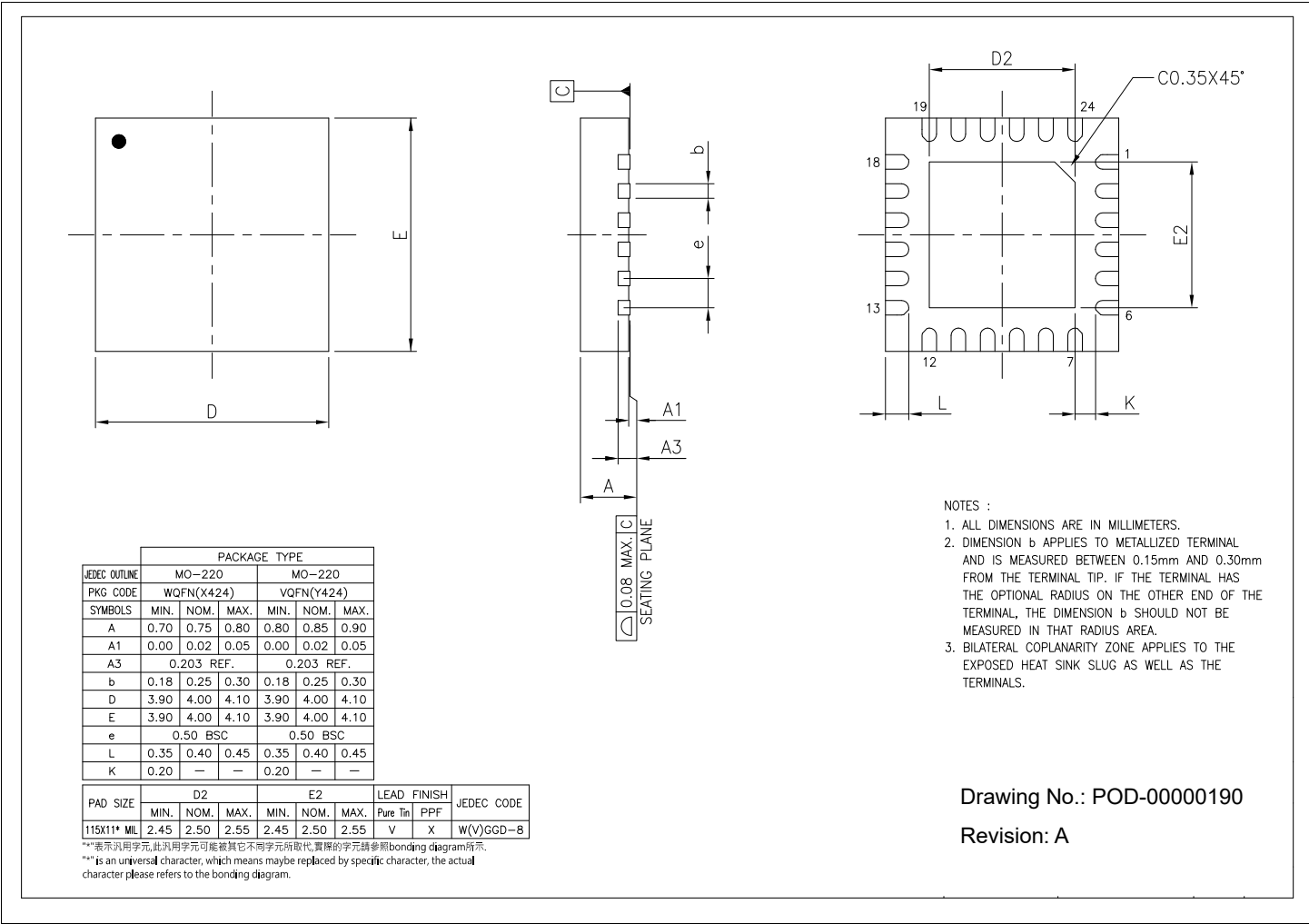


Figure 9: QFN-24 Mechanical Dimensions

Ordering Information

Table 9: Ordering Information

Ordering Part Number	Package	Number of GPIOs	Operating Temperature Range	Packing Method	Lead-Free
MXL82403I-AGA-R	TSSOP-24	16	–40°C to 85°C	Tape and Reel	Yes
MXL82423I-AQB-R	QFN-24	16	–40°C to 85°C	Tape and Reel	Yes

Note: For more information about part numbers, as well as the most up-to-date ordering information and additional information on environmental rating, go to www.maxlinear.com/MxL82403 and www.maxlinear.com/MxL82423.



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